Specifications



variable speed drive ATV12 - 2.2kW - 3hp - 200..240V - 1ph - with heat sink

ATV12HU22M2

Main

Main	
Range of product	Altivar 12
Product or component type	Variable speed drive
Product specific application	Simple machine
Mounting mode	Cabinet mount
Communication port protocol	Modbus
Supply frequency	50/60 Hz +/- 5 %
[Us] rated supply voltage	200240 V - 1510 %
Nominal output current	10 A
Motor power hp	3 hp
Motor power kW	2.2 kW
	3 hp
EMC filter	Integrated
IP degree of protection	IP20
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Complementary 4 **Discrete input number** 2 Discrete output number 1 Analogue input number 1 Analogue output number Relay output number 1 2-wire RS 485 **Physical interface Connector type** 1 RJ45 10 A at 4 kHz Continuous output current Method of access Server Modbus serial Speed drive output frequency 0.5...400 Hz Speed range 1...20 20 ms, tolerance +/- 1 ms for logic input Sampling duration 10 ms for analogue input +/- 0.3 % of maximum value for analogue input Linearity error **Frequency resolution** Analog input: converter A/D, 10 bits



	Display unit: 0.1 Hz
Time constant	20 ms +/- 1 ms for reference change
Transmission rate	9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
Transmission frame	RTU
Number of addresses	1247
Data format	8 bits, configurable odd, even or no parity
Communication service	Read holding registers (03) 29 words Write single register (06) 29 words Write multiple registers (16) 27 words Read/write multiple registers (23) 4/4 words Read device identification (43)
Type of polarization	No impedance
4 quadrant operation possible	False
Asynchronous motor control profile	Sensorless flux vector control Quadratic voltage/frequency ratio Voltage/frequency ratio (V/f)
Maximum output frequency	4 kHz
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor
Acceleration and deceleration ramps	Linear from 0 to 999.9 s U S
Motor slip compensation	Adjustable Preset in factory
Switching frequency	216 kHz adjustable 416 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Braking to standstill Brake chopper integrated	By DC injection False
Brake chopper integrated	False 24.0 A at 100 V (heavy duty)
Brake chopper integrated	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty)
Brake chopper integrated Line current Maximum input current	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A
Brake chopper integrated Line current Maximum input current Maximum output voltage	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty)
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty)
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high overload	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA 10.0 A
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high overload Power dissipation in W With safety function Safely	False 24.0 A at 100 V (heavy duty) 20.2 A at 120 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 15.0 A during 60 s (heavy duty) 5060 Hz 5 % 1 kA 10.0 A Forced cooling: 93.0 W
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high overload Power dissipation in W With safety function Safely Limited Speed (SLS) With safety function Safe brake	False 24.0 A at 100 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA 10.0 A Forced cooling: 93.0 W False
Brake chopper integrated Line current Maximum input current Maximum output voltage Apparent power Maximum transient current Network frequency Relative symmetric network frequency tolerance Prospective line lsc Base load current at high overload Power dissipation in W With safety function Safely Limited Speed (SLS) With safety function Safe brake management (SBC/SBT) With safety function Safe	False 24.0 A at 100 V (heavy duty) 20.2 A 240 V 4.8 kVA at 240 V (heavy duty) 15.0 A during 60 s (heavy duty) 16.5 A during 2 s (heavy duty) 5060 Hz 5 % 1 kA 10.0 A Forced cooling: 93.0 W False False

With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	False
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	False
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Line supply overvoltage Line supply undervoltage Overcurrent between output phases and earth Overheating protection Short-circuit between motor phases Against input phase loss in three-phase Thermal motor protection via the drive by continuous calculation of I ² t
Tightening torque	1.2 N.m
Insulation	Electrical between power and control
Quantity per set	Set of 1
Width	105 mm
Height	142 mm
Depth	156.2 mm
Net weight	1.4 kg
Environment	
Operating altitude	> 10002000 m with current derating 1 % per 100 m <= 1000 m without derating
Operating position	Vertical +/- 10 degree
Product certifications	NOM CSA C-Tick UL GOST RCM KC
Marking	CE
Standards	UL 508C UL 618000-5-1 EN/IEC 61800-5-1 EN/IEC 61800-3
Assembly style	With heat sink
Electromagnetic compatibility	Electrical fast transient/burst immunity test level 4 conforming to EN/IEC 61000-4-4 Electrostatic discharge immunity test level 3 conforming to EN/IEC 61000-4-2 Immunity to conducted disturbances level 3 conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to EN/IEC 61000-4-3 Surge immunity test level 3 conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz

20 Oct, 2022

Volume of cooling air

Life Is On Schneider

16 m3/h

Overvoltage category	Class III
Regulation loop	Adjustable PID regulator
Electromagnetic emission	Radiated emissions environment 1 category C2 conforming to EN/IEC 61800-3 216 kHz shielded motor cable Conducted emissions with integrated EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 2, 4, 8, 12 and 16 kHz shielded motor cable <5 m Conducted emissions with additional EMC filter environment 1 category C1 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <20 m Conducted emissions with additional EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with additional EMC filter environment 2 category C3 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 412 kHz shielded motor cable <50 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 416 kHz shielded motor cable <50 m Conducted emissions with integrated EMC filter environment 1 category C2 conforming to EN/IEC 61800-3 416 kHz shielded motor cable <50 m
Vibration resistance	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) - drive unmounted on symmetrical DIN rail - conforming to EN/IEC 60068-2-6
Shock resistance	15 gn conforming to EN/IEC 60068-2-27 for 11 ms
Relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
Noise level	45 dB
Pollution degree	2
Ambient air transport temperature	-2570 °C
Ambient air temperature for operation	-1050 °C without derating 5060 °C with current derating 2.2 % per °C
Ambient air temperature for storage	-2570 °C

Packing Units

Unit Type of Package 1	PCE
Package 1 Length	20 cm
Number of Units in Package 1	1
Package 2 Width	60 cm
Package 2 Height	75 cm
Package 2 Weight	65.95 kg
Package 3 Height	80 cm
Package 1 Width	18 cm
Package 1 Height	20 cm
Package 1 Weight	1.753 kg
Number of Units in Package 2	30
Unit Type of Package 2	P06
Package 2 Length	80 cm

Offer Sustainability

Sustainable offer status	Green Premium product
REACh Regulation	REACh Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS declaration

Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Contractual warranty

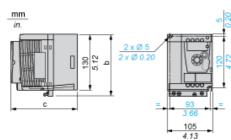
Warranty

18 months

Dimensions Drawings

Dimensions

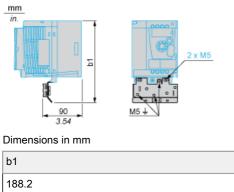
Drive without EMC Conformity Kit



Dimensions in mm

b	c
142	156.2
Dimensions in in.	·
b	c
5.59	6.15

Drive with EMC Conformity Kit



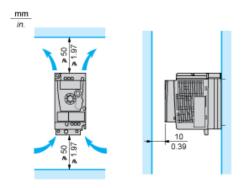
o1	
188.2	
Dimensions in in.	
51	
7.41	

Mounting and Clearance

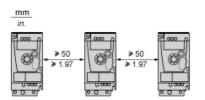
ATV12HU22M2

Mounting Recommendations

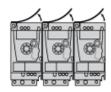
Clearance for Vertical Mounting



Mounting Type A

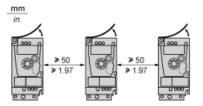


Mounting Type B



Remove the protective cover from the top of the drive.

Mounting Type C

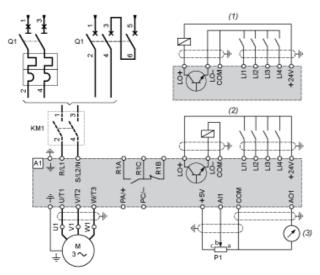


Remove the protective cover from the top of the drive.



Connections and Schema

Single-Phase Power Supply Wiring Diagram



- Drive Contactor (only if a control circuit is needed) 2.2 kΩ reference potentiometer. This can be replaced by a 10 kΩ potentiometer (maximum). Circuit breaker Negative logic (Sink) Positive logic (Source) (factory set configuration) 0...10 V or 0...20 mA
- A1 KM1 P1 Q1 (1) (2) (3)

Connections and Schema

Recommended Schemes

2-Wire Control for Logic I/O with Internal Power Supply



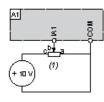
LI• : Reverse A1 : Drive

3-Wire Control for Logic I/O with Internal Power Supply



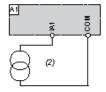
LI• : Reverse A1 : Drive

Analog Input Configured for Voltage with Internal Power Supply



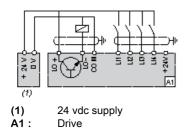
(1) A1 : 2.2 k $\Omega...10$ k Ω reference potentiometer Drive

Analog Input Configured for Current with Internal Power Supply

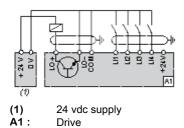


(2) A1 : 0-20 mA 4-20 mA supply Drive

Connected as Positive Logic (Source) with External 24 vdc Supply



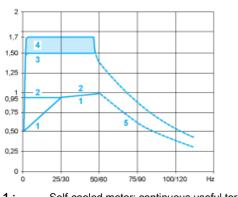
Connected as Negative Logic (Sink) with External 24 vdc supply



ATV12HU22M2

Performance Curves

Torque Curves



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s 4:
- Transient overtorque for 2 s 5: Torque in overspeed at constant power (2)
- For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies.
- (1) (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the